



AM3042 | Servomotor 3.35 Nm (standstill torque)

Data for 400 V AC	AM3042-wCyz-0000	AM3042-wEyz-0000	AM3042-wGyz-0000
Standstill torque	3.35 Nm	3.42 Nm	3.53 Nm
Rated torque	3.10 Nm	2.81 Nm	2.35 Nm
Rated speed	1500 min ⁻¹	3500 min ⁻¹	6000 min ⁻¹
Rated power	0.49 kW	1.03 kW	1.48 kW
Peak torque	12.81 Nm	13.0 Nm	13.2 Nm
Standstill current	1.40 A	2.74 A	4.80 A
Peak current	7.0 A	13.7 A	24.0 A
Torque constant	2.4 Nm/A	1.26 Nm/A	0.74 Nm/A
Voltage constant	154 mV/min ⁻¹	80.9 mV/min ⁻¹	47.5 mV/min ⁻¹
Number of poles	10		
Rotor moment of inertia	1.450 kgcm ²		
Weight	3.39 kg		
Holding torque brake (M_{br})	6 Nm		
Power consumption (brake) at 24 V DC (P_{br})	13 W		
Rotor moment of inertia incl. brake (J)	1.581 kg cm ²	1.518 kg cm ²	1.518 kg cm ²
Weight incl. brake (m)	4.02 kg		

Order reference AM30uv-wxyz-000a	
u	flange code
v	motor length
w = 0	smooth shaft (standard)
w = 1	shaft with groove and feather key according to DIN 6885
w = 2	shaft with IP 65 sealing ring and smooth shaft (AM304x to AM308x)
w = 3	shaft with IP 65 sealing ring and shaft with groove and feather key (AM304x to AM308x)
x	winding code A...T
y = 0	resolver, 2-pole
y = 1	single-turn absolute encoder, EnDat 2.1, absolute position within one revolution, electronic identification plate, AM302x...AM304x: 512 sine periods per revolution, AM305x...AM308x: 2,048 sine periods per revolution
y = 2	multi-turn absolute encoder, EnDat 2.1, absolute position within 4,096 revolutions, electronic identification plate, AM302x...AM304x: 512 sine periods per revolution, AM305x...AM308x: 2,048 sine periods per revolution
y = 3	single-turn absolute encoder, BiSS, absolute position within one revolution, electronic identification plate, AM302x...AM308x: 2,048 sine periods per revolution
y = 4	multi-turn absolute encoder, BiSS, absolute position within 4,096 revolutions, electronic identification plate, AM302x...AM308x: 2,048 sine periods per revolution
z = 0	without holding brake
z = 1	with holding brake for AM302x...AM308x
a = 0	rotatable angular connectors for motor and feedback cable (only for AM302x up to AM307x)
a = 3	vertical connectors for motor and feedback cables (only for AM302x up to AM307x)
	The options cannot be installed in the field. Options such as shaft seal, holding brake, absolute encoder can lead to a reduction of the nominal rating.
	All electric quantities are RMS values.